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# **GENERAL PRESENTATION**

This product complies with the "safety, specific rules for powering vertically opening garage doors in residential use" requirements (standard EN 60335-2.95). When installed in line with these instructions and in compliance with the "Installation Checklist", the product will be compliant with standards EN 13241-1 and EN 12453.

The instructions referred to in the installation manual and instructions for use of this product are designed to prevent damage to property and personal injury along with compliance with the above standards. Failure to comply with these instructions absolves Somfy from any liability resulting from damage that may be caused. Dexxo Pro is a product that must be installed inside the garage with an integrated back-up control system.

Somfy hereby declares that the device is compliant with the essential demands and other relevant requirements of directive 1999/5/CE. A declaration of compliance is available from the web site at www.somfy.com/ce (Dexxo Pro). This product is suitable for use in the European Union and in Switzerland.

# SAFETY INSTRUCTIONS

### Caution

These are important safety instructions. Always follow the instructions, incorrect installation may lead to serious injury.

### Safety instructions

Before installing the motor drive unit, remove all unessential lines or chains and switch off all equipment that is not essential for motorised door operation. Before installing the motor drive unit, make sure that the door is in good mechanical condition, that it is properly balanced and that it opens and closes correctly.

Locate all control systems at least 1.5 metres above floor level, making sure that they are visible from the entrance to the garage but safe from moving parts. Position the manual release cord no more than 1.8 metres above floor level.

Where a removable release mechanism is used, we recommend storing it close to the door.

Fix the label describing the manual release procedure close to the release mechanism.

Fix the warning labels describing the hazards of door motion close to any fixed control mechanisms installed and make sure that the labels are clearly visible to the user.

After installation, make sure that the mechanism is correctly adjusted and that the motor drive unit reverses its motion when the door encounters an obstacle that is at least 50 mm from floor level.

After installation, make sure that no part of the door overhangs an area accessible to the public.

After installation, make sure that the motor drive unit inhibits or stops the door opening motion when the door is loaded down with a 20 kg weight attached to a central position of the door's bottom edge.

## **PRODUCT DESCRIPTION**

### Product components Fig. 1

| Key. | Number | Description                   | Key. | Number | Description                        |
|------|--------|-------------------------------|------|--------|------------------------------------|
| 1    | 1      | Motor head                    | 15   | 6      | HU8 nut                            |
| 2    | 1      | Motor cover                   | 16   | 2      | Shaft                              |
| 3    | 1      | Built-in light cover          | 17   | 2      | Circlips                           |
| 4    | 1      | Lintel bracket                | 19   | 4      | Self-shaping Ø 4x8 screw           |
| 5    | 1      | Door bracket                  | 20   | 2      | Special screw for plastic Ø 3.5x12 |
| 6    | 2      | Ceiling bracket               | 21a  | 1      | Single part rail                   |
| 7    | 2      | Motor head bracket            | 21b  | 1      | Two part rail                      |
| 8    | 1      | Manual release cord           | 21b1 | 1      | Sleeve                             |
| 9    | 1      | Link arm                      | 21b2 | 8      | Self-shaping Ø 4x8 screw           |
| 10   | 1      | Travel stop                   | 22   | 2      | HM8 self-locking nut               |
| 11   | 4      | Chain retainer pad            | 23   | 2      | Bracket                            |
| 12   | 1      | Power cable                   | 24   | 1      | Spacer                             |
| 13   | 2      | Hex. head M8x16 bolt          | 25   | 2      | Keygo remote control               |
| 14   | 4      | Hex. head M8x12 bolt & washer | 26   | 1      | 24 V 21 W BA15s socket light bulb  |

### Area of application Fig. 2

#### Types of doors (Fig.2)

A: Projecting up and over door.

B: Sectional door:

- if the door's upper profile is a specific one, use the "sectional door mounting bracket" ref.: 9009390.
- if the door surface exceeds 10 sq. metres, use the "sectional door adapter" ref.: 2400873.
- C: Sideways opening sliding door:
- for side wall mounting, use:
- a belt transmission rail
- an "adjustable cranked arm" ref.: 9014481.
- for ceiling mounting, use:
- an "articulated arm" ref.: 9014482.
- D: Swinging door. Use the swinging door kit, ref.: 2400459.
- E: Semi and non projecting door. Use:
  - a high performance transmission rail
  - "the semi and non projecting door kit" ref.: 2400458.

Some doors of this type may prove impossible to automate. Contact SOMFY's technical department.

### Door dimensions (Fig. 3)

For maximum door heights, the motor travel can be optimised:

- By installing the motor head at a 90° angle (Fig. 7- ()).
- By fixing the lintel bracket to the ceiling, behind the lintel itself by up to 200 mm (Fig. 5- 1)
- By cutting the link arm to size.

## POINTS TO CHECK PRIOR TO INSTALLATION

### Preliminary checks

Check the garage door can be operated manually and runs smoothly. Ensure the door is in good mechanical condition (pulleys, mounts...) and is correctly balanced (spring tension).

Remember that any work performed on door springs may be dangerous.

The structure of your garage (walls, lintel, inside surfaces, cross members, door rails...) are used to mount the Dexxo Pro system. Reinforce them where necessary.

Never splash water onto the system. Never install Dexxo Pro in a location where water may cause damage.

The bottom edge of the door should be fitted with a rubber strip to avoid hard contact and enhance the contact surface.

If the garage door is the only entry point into the garage, fit an external release (external release keylock (ref. 9012961) or an external release (ref. 9012962) and include a back-up battery (ref. 9001001).

If the garage door includes a separate pedestrian door, the door must be fitted with an interlock to prevent garage door movement when the pedestrian door is open (pedestrian door safety kit ref. 2400657).

If the garage door opens on to a public road, install an indicator light, such as a flashing orange light (ref. 9015171).

If the garage door operates in automatic mode, install a photoelectric cell type safety system (ref. 9014994 or ref. 9013647) and a flashing orange light type indicator.

Make sure that the door does not comprise any accessible parts.

Unlocking the door may trigger uncontrolled door movement if the door is not balanced correctly.

### Safety instructions

Safety instructions must be complied with throughout the installation process:

- · Take off any personal jewellery (bracelet, chain or others) during installation work.
- During drilling and welding work, always wear safety glasses and suitable protection.
- · Always use suitable tools.
- Take care when handling the motor drive system.
- Never connect the mains power supply or the battery back-up system before completing the installation process.
- · Never use high pressure water systems for cleaning purposes.

## INSTALLATION

### Installation height Fig. 4

Measure the distance "D" between the door's highest point and the ceiling.

If "D" is between 35 and 200 mm, mount the complete system straight onto the ceiling.

If "D" exceeds 200 mm, mount the complete assembly so that the height "H" falls between 10 and 200 mm.

### Detailed description of installation steps Fig. 5 to 15

Mounting the lintel bracket and the door bracket (Fig. 5)

When installing the system directly onto the ceiling (flush with the ceiling), the lintel bracket can be mounted on the ceiling, if necessary recessed from the lintel by up to 200 mm max. (Fig. 5-

#### Assembling the two part rail (Fig. 6)

[1] [2] [3]. Unfold the two parts of the rail.

#### Ensure that the chain or belt is not twisted.

[4]. Assemble the two parts of the rail using the sleeve.

[5]. Mount the complete assembly using the eight mounting screws.

[6]. Tighten the nut to tension the chain or belt. The compressed rubber must measure 18 and 20 mm.

The mounting screws must not penetrate the rail (do not drill).

When installing the system directly onto the ceiling, do not use the sleeve mounting screws.

### Fitting the rail onto the motor head (Fig. 7)

### Fitting the complete assembly onto the garage ceiling (Fig. 8 to 10)

### Fitting to the lintel bracket (Fig. 8)

#### Ceiling mounting

- Flush with the ceiling: mount the system directly onto the ceiling using the rail (Fig. 9). It is possible to add mounting points at the motor head level (Fig. 9- 1).
- Hung from the ceiling: two options:
  - mount the system at the motor head (Fig. 10- a).
  - mount the system at the rail (Fig. 10- b).

To add an adjustable intermediate mounting along the rail, or a mounting at a dimension h between 250 mm and 550 mm, use the ceiling mounting kit ref.: 9014462 (Fig. 10- )).

### Fitting the arm onto the door and the trolley (Fig. 11)

- [1]. Release the trolley using the manual release cord.
- [2]. Bring the trolley up to the door.
- [3]. Attach the arm to the door bracket and the trolley.

#### Adjusting and fastening the opening travel stop (Fig. 12)

- Release the trolley from the runner using the manual release mechanism and bring the door to the open position. Do not open the door fully, but position it so that it does not reach its own travel stop.
- [2]. Slot the travel stop (10) into the rail then turn it by  $90^{\circ}$ .
- [3]. Position the travel stop against the trolley.

[4]. Moderately tighten down the mounting screw.

Do not tighten the mounting screw all the way down. Excessive tightening can damage the screw and cause the travel stop not to remain in place.

#### Fitting the chain retainer pads (Fig. 13)

#### For chain rails only.

These pads are used to limit spurious noise linked to chain friction within the rail. Position each of the pads in the first hole in the rail after the travel stop. Make sure that the pad is pressed in all the way so that its positioning pin is accessible outside of the rail.

#### Checking the chain or belt tension (Fig. 14)

The rails are supplied ready tensioned and inspected. If necessary, adjust the tensioning.

The rubber or tension spring must never be fully compressed during operation.

#### Connecting the mains power supply (Fig. 15)

- [1]. Remove the motor cover and the protective sheet.
- [2]. Fit the light bulb.
- [3]. Connect to the mains supply.

Plug the power cable into a suitable power outlet that complies with electric power requirements. The electric supply must be suitably protected (a fuse or circuit breaker with a 5 A rating) and a residual current device (30 mA).



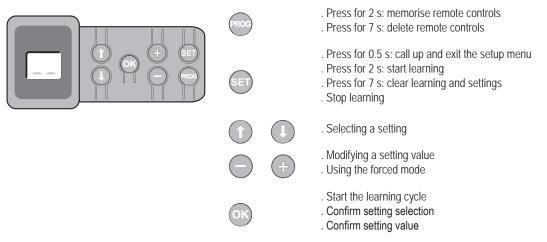
An omnipolar disconnection mechanism must be provided for the power supply: . by using a power cord with a mains splug that can be disconnected, or . by fitting a switch that ensures a contact separation distance of at least 3 mm for each pole (refer to standard EN60335-1).



*Make sure that the manual release cord is located at a maximum height of 1.80 metres off the ground. If necessary, extend the cord.* 

# PROGRAMMING

### Programming button description



### End limit setting and self-learning Fig. 16

For swinging doors, change the P9 setting before starting self-learning.

 Press the "SET" button until the light comes on (2 s). The display shows "S2"

- [2]. Control the motor using the "+" or "-" buttons so that the transmission system runner moves to link up with the trolley and closes the door.
  - Pressing and holding the "-" button closes the door.
     Release the "-" button before the motor has time to force against the door.
  - Pressing and holding the "+" button opens the door.
- [3]. Adjust the closed position using the "+" or "-" buttons.
  - Release the "-" button before the motor has time to force against the door.
- [4]. Press "OK" to validate the closed end limit position and start the self-learning cycle.
  - The door runs through a complete Open Close cycle.
  - If learning was correct, the display will show "C1".
  - If the learning cycle was not completed correctly, the display will show "S1".

During the learning cycle:

- If the door is moving, pressing any button will stop the movement and interrupt the learning mode.
- If the door is stopped, pressing "SET" once will exit the learning mode.

You can call up the learning mode at any time, even when the learning cycle has already been executed and the display shows "C1".

### Memorising the remote controls for operation in «Total opening» mode Fig. 17

Up to 32 control channels can be stored.

Running this procedure for a previously stored channel will clear it.

### At this stage in the installation process, the Dexxo Pro motor drive unit is ready to run.

## **OPERATING TEST**

### Using the remote controls Fig. 18

### Obstacle detection function Fig. 19 and 20

The detection of an obstacle during door opening will stop the door (Fig. 19).

The detection of an obstacle during door closure will reopen the door (Fig. 20).

Make sure that obstacle detection works when the door encounters an obstacle 50 mm from the ground.

### Built in lighting operation

The light will come on every time the motor drive unit is operated. It will go out automatically after one minute once the door stops. This time delay is adjustable (refer to the Setup chapter). Repetitive use which causes the light to stay on continually may result in an automatic cut-off condition triggered by the thermal cut out protection mechanism.

# **CONNECTING PERIPHERALS**

### Description of the various peripherals Fig. 21

| Кеу | Description     | Кеу | Description                |
|-----|-----------------|-----|----------------------------|
| 1   | Orange light    | 7   | Pedestrian door safety kit |
| 2   | Remote lighting | 8   | Photoelectric cells        |
| 3   | Code keypad     | 9   | Reflex type cells          |
| 4   | Keyswitch       | 10  | Sensor bar                 |
| 5   | Aerial          | 11  | Siren                      |
| 6   | Battery         |     |                            |

### Electrical connections for the various peripherals Fig. 21 to 30

Cut the electric power supply to the motor before performing any work on peripherals. If the display remains off after working on the system, check the wiring (for possible short circuits or polarity reversals).

### General electrical diagram (Fig. 21)

#### Photoelectric cells (Fig. 22)

Two types of connections can be made:

- A: Standard (without self test): program the setting "P2" = 2.
- B: With self test: program the setting "P2" = 1.
- This means that an automatic test is conducted to check photoelectric cell operation every time the door operates. If the test fails, no door movement is possible.

#### Reflex photoelectric cell (Fig. 23)

With self test: program the setting "P2" = 1. This means that an automatic test is conducted to check photoelectric cell operation every time the door moves. If the test fails, no door movement is possible.

#### Sensor bar (Fig. 24)

With self test: program the setting "P2" = 1.

This is used to perform an automatic test of sensor bar operation every time the door moves.

If the test result is negative, no door movement is possible.

### Make sure you have correctly configured parameter "P2" taking into account the photoelectric cells or the sensor bar.

#### Orange light (Fig. 25)

Program the setting "P1" depending on the required operating mode:

- Without warning before door movement: "P1" = 0.
- With a 2 s warning before door movement: "P1" = 1.

#### Code keypad (Fig. 26)

Pedestrian door safety kit (Fig. 27)

When the pedestrian door contact is fitted, it must be connected in place of the jumper normally fitted between terminals 5 and 6.

#### If the pedestrian door contact is removed, the jumper between terminals 5 and 6.

#### Battery (Fig. 28)

Aerial (Fig. 29)

Remote lighting (Fig. 30)

Class 2 (double insulation) light units that are connected do not require an earth connection.

Various types of lighting can be connected without exceeding a total power consumption of 500 W.

#### Siren

For more information on connecting the siren, consult the installation manual.

Programme the parameter "Pb" to activate the siren:

• Siren inactive "Pb" = 0.

• Siren active: "Pb" = 1 or "Pb" = 2.

# SETUP

# General setup diagram Fig. 31

## Meanings of the various parameters

| Code     | Description                                     | Values   | Comments  |  |  |
|----------|---|--|---|--|--|
| P0       | Total operating mode                            | 0: sequential  | Each press on the remote control causes the motor to move (initial position: door closed) as per the following cycle: open, stop, close, stop, open   |  |  |
|          |   | 1: sequential + timed close  | In sequential mode with automatic timed close:<br>- the door is closed automatically after the timed<br>programmed in parameter "t0",<br>- pressing a button on the remote control interru<br>movement taking place and the timed close.  |  |  |
|          |   | 2: automatic closure   | Automatic closure<br>mode operation<br>is only possible if<br>photoelectric cells<br>are fitted, i.e. P2=1<br>or P2=2.  | In automatic closure mode:<br>- the door is closed automatically after the timed delay<br>programmed in parameter "t0",<br>- pressing a button on the remote control during<br>opening has no effect,<br>- pressing a button on the remote control during closing<br>causes it to reopen,<br>- pressing a button on the remote control during the<br>timed close restarts the timed delay.                                       |  |
|          |   | 3: automatic closure by cells  | 0112-2.   | After the door is opened, movement in front of the cells<br>(safe closure) will close the door after a short timed<br>delay (fixed at 5 seconds).<br>If there is no movement in front of the cells, the door w<br>close automatically after the timed close programmed is<br>parameter "t0".<br>If there is an obstacle in the cells' detection zone, the<br>door will not close. It will close once the obstacle is<br>removed. |  |
| P1       | Orange warning light                            | 0: without advance warning<br>1: with 2 s advance warning  | If the garage opens onto a public road, always select with advance warning: P1=1.   |  |  |
| P2       | Safety input                                    | 0: no safety mechanism<br>1: safety mechanism with self test<br>2: safety mechanism without self test  | If value 0 is selected, the safety input is not taken into account.<br>If value 1 is selected, the system's self test is run at the start of every<br>operating cycle.<br>If value 2 is selected, the safety system runs without a self test: it is essential<br>to test its proper operation every six months.   |  |  |
| P3       | Obstacle detection sensitivity                  | 0: low sensitivity<br>1: low sensitivity<br>2: standard<br>3: high sensitivity   | If this setting is changed, it is essential to run the force measurement sequence at the end of the installation procedure or install a sensor bar.   |  |  |
| P4       | Partial operating mode                          | 0: sequential  | Each press on the remote control causes the motor to move (initial position door closed) as per the following cycle: open, stop, close, stop, open  |  |  |
|          |   | 1: sequential + timed close  | Automatic closure mode operation is only possible if photoelectric cells are<br>fitted, i.e. P2=1 or P2=2.<br>In sequential mode with automatic timed close:<br>- the door is closed automatically after the timed delay programmed in<br>parameter "t2",<br>- pressing a button on the remote control interrupts the movement taking place<br>and the timed close. |  |  |
| P5       | Closing speed                                   | 0: slowest speed: approx. 3.5 cm/s<br>to<br>9: fastest speed: approx. 18 cm/s<br>By default, 6: approx. 12 cm/s                                    | If this setting is changed, it is essential to run the force measurement sequence at the end of the installation procedure or install a sensor bar.   |  |  |
| P6       | Partially open position                         | Storing the position as illustrated in Fig. 33.  |   |  |  |
| P6<br>P7 | Closure approach speed                          | <ul> <li>Storing the position as indistrated in Fig. 33.</li> <li>0: no slowdown</li> <li>1: short soft stop</li> <li>2: long soft stop</li> </ul> | P7=0: the door does not slow before closure.<br>P7=1: the door speed slows 20 centimetres before closure.<br>P7=2: the door speed slows 50 centimetres before closure.<br>If this setting is changed, it is essential to run the force measurement<br>sequence at the end of the installation procedure or install a sensor bar.                                    |  |  |
| P8       | Opening speed                                   | 0: slowest speed: approx. 3.5 cm/s<br>to<br>9: fastest speed: approx. 18 cm/s  |   |  |  |
| P9       | Choice of operating direction<br>(type of door) |  | If this setting requires with self-learning.  | s modification the end limit setting must be repeated alon   |  |
|          |   | 1: direction 2: swinging doors   |   |  |  |

| Code | Description                                     | Values   | Comments  |
|------|---|--|---|
| PA   | Maintenance required indicator                  | 0: no indication<br>1: 100 cycles<br>to<br>99: 9900 cycles<br>(number of cycles = value x 100 cycles)        | Once the motor reaches the programmed number of cycles, the integrated light flashes each time the door moves to signal that maintenance is required. To stop the integrated light flashing, either the current value must be confirmed or modified, or the maintenance indicator must be deactivated.  |
| Pb   | Detection of forced entry                       | 0: no detection of forced entry<br>1: obvious forced entry detected<br>2: less obvious forced entry detected | Detection of forced entry starts operating 30 seconds after the door is closed.<br>If forced entry is detected, the siren sounds for 2 minutes. To stop it, press one<br>of the buttons on the remote control.<br>If photoelectric cells are installed (P2=2), these must be connected to the<br>permanent power supply (refer to the installation manual for the siren). |
| A0   | Safety action prior to opening (safety ADMAP)   | 0: no effect<br>1: movement rejected   | If value 1 is selected, triggering the safety input will inhibit door opening.  |
| A1   | Safety action during closure                    | 1: stop<br>2: stop + partial re-opening<br>3: fully reopen   | Value 1 is not allowed when using a sensor bar on the safety input.   |
| A2   | Obstacle detection action during closure        | 2: stop + partial re-opening<br>3: fully reopen  |   |
| tO   | Total operating mode automatic timed close      | 0 to 12 (time delay value = value x 10 s)<br>2: 20 s   |   |
| t1   | Lighting time delay                             | 0 to 60 (time delay value = value x 10 s)<br>6: 60 s   |   |
| t2   | Partial operating mode<br>automatic timed close | 0 to 12 (time delay value = value x 10 s)<br>2: 20 s   |   |

(Boldface text = default values)

Programming example: setting the "P7" closure approach speed (Fig. 32)

Setting up a long soft stop function zone "P7" = 2.

Special case: adjusting the position of the door for partial opening (Fig. 33)

Select setting "P6" and validate by pressing "OK".

Move the door to the desired partially open position:

. Pressing and holding the "-" button will close the door.

. Pressing and holding the "+" button will open the door.

. Validate by pressing "OK".

. Exit the menu with "SET".

### Forced mode (Fig. 34)

This function is used to move the door to a specific position:

. Pressing and holding the "-" button will close the door.

. Pressing and holding the "+" button will open the door.

Memorising the remote control for operation in «Partial opening» mode (Fig. 35)

Memorising the remote control for controlling remote lighting (Fig. 36)

Memorising a Telis or similar type remote control (Fig. 37)

## SPECIAL OPERATION

Refer to the User's Manual page 4.

Adding a remote control without accessing the motor head (see user guide on page 5)

With a Keygo (Fig. 12a) With a Telis or similar (Fig. 12b) CLEARING REMOTE CONTROLS AND ALL SETTINGS

### Clearing remote controls Fig. 38

Press the "PROG" button until the light blinks (7 s). This clears all of the remote controls memorised.

### Resetting all settings Fig. 39

Press the "SET" button until the light goes out (7 s).

This clears all previously stored settings and returns them to their default values.

# LOCKING PROGRAMMING (Fig. 40)

Used to lock the programming settings (end limit setting, self-learning, setup).

Simultaneously press the "SET", "+" and "-" buttons:

- start by pressing "SET".

- pressing "+" and "-" must take place within two seconds.

To access programming mode once again, repeat the same procedure.

## **REFITTING COVERS (Fig. 41)**

Position the aerial and fit the covers.

To ensure proper remote control range, the aerial must be fitted in one of the two positions shown in Figure 41.

# TROUBLESHOOTING

### Operating codes displayed

| Code | Description   | Comments   |
|------|---|--|
| C1   | Waiting for a command                                 |  |
| C2   | Door opening  |  |
| C3   | Waiting for the door to close                         |  |
| C4   | Door closing  |  |
| C5   | Obstacle detection                                    | Displayed during obstacle detection then for 30 s.   |
| C6   | Safety input active                                   | Displayed after a movement request or during movement, when the safety input is active.<br>This display is maintained as long as the safety input is active.                       |
| C9   | Pedestrian door safety contact active                 | Displayed after a movement request or during movement, when the pedestrian door contact is open.<br>The display is maintained as long as the pedestrian door contact remains open. |
| Са   | Safety mechanism self test                            | Displayed during safety mechanism self tests.  |
| Cb   | Permanent hardwired control                           | Indicates that the permanent hardwired control input is activated (contact closed). Commands from radio remote control units are inhibited.  |
| Cd   | Working from back-up battery<br>Waiting for a command |  |

## Programming codes displayed

| Code | Description  | Comments  |  |
|------|--|---|--|
| S1   | Awaiting setting   | Pressing the "SET" button for 2 s starts the learning mode.   |  |
| S2   | Learning mode  | Pressing the "OK" button starts the learning cycle: the S2 display blinks during the entire cycle.<br>Pressing the "+" or "-" buttons will control the motor in forced mode.  |  |
| F0   | Awaiting remote control memorisation for<br>operation in total opening | Pressing a button on the remote control allocates this button to the motor total opening control.<br>Pressing "PROG" once more switches to "awaiting remote control memorisation for operation in partial opening:<br>F1" mode.     |  |
| F1   | Awaiting remote control memorisation for operation in partial opening  | Pressing a button on the remote control allocates this button to the motor partial opening control.<br>Pressing "PROG" once more switches to "awaiting remotely controlled lighting memorisation: F2" mode                          |  |
| F2   | Awaiting remotely controlled lighting memorisation                     | Pressing a button on the remote control allocates this button to the remotely controlled lighting control.<br>Pressing "PROG" once more switches to "awaiting remote control memorisation for operation in total opening: F0" mode. |  |

## Error and failure codes displayed

| Code     | Description                         | Comments   | Action required?  |
|----------|-------------------------------------|--|---|
| E2       | Safety input always active          | Displayed when the safety input remains active for more than three minutes.  | Check that there is no obstacle triggering cell or sensor bar<br>detection.<br>Check that "P2" is setup correctly depending on the devices<br>connected to the safety input.<br>Check safety device wiring.<br>When photoelectric cells are used, check their proper alignment. |
| E4       | Safety mechanism self test fault    | The safety device self test failed   | Check that "P2" is setup correctly depending on the devices<br>connected to the safety input.<br>Check safety device wiring.<br>When photoelectric cells are used, check their proper alignment.  |
| Eb<br>Ec | Other faults and failure conditions | These codes correspond to various electronic circuit board failures.   | Cut the power supply (mains & battery back-up), wait for a few minutes then re-connect the power supply.<br>Perform a learning cycle.<br>If the fault persists, contact Somfy Technical Support.  |
| H1       | Detection of forced entry           | Displayed when an action occurs from<br>outside the garage (read by reinjection<br>of power)   | Press a button on the memorised remote control to stop the siren.<br>Start a complete opening and closing cycle.  |
| H2       | Detection of forced entry           | Displayed when an action occurs from<br>outside the garage (read by optical<br>encoder)  | Press a button on the memorised remote control to stop the siren.<br>Start a complete opening and closing cycle.  |
| CC       | Maintenance is required             | Displayed when maintenance is required<br>on the installation. The number of cycles<br>programmed in parameter "PA" has been<br>reached. | Confirm or modify the current "PA" value, or deactivate the<br>"Maintenance required indicator" function.   |

## Accessing stored data

To access stored data, select the "Ud" setting then press "OK" as shown in Fig. 31.

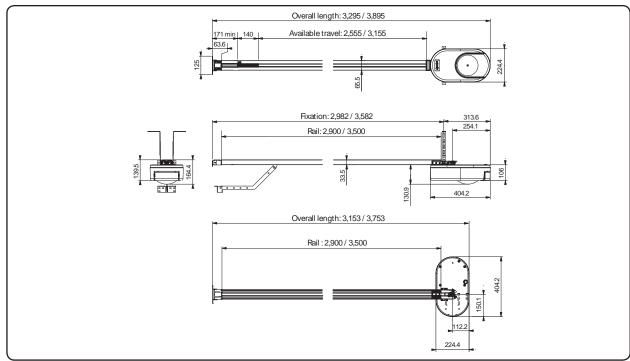
| Data     | Description   |  |
|----------|---|--|
| U0       | Total cycle counter: tens and units                   |  |
| U1       | Total cycle counter: thousands and hundreds           |  |
| U2       | Total cycle counter: hundreds of thousands            |  |
| U3       | Cycle counter with obstacle detection: tens and units |  |
| U4       | Cycle counter with obstacle detection: thousands      |  |
| U5       | Number of control channels memorised                  |  |
| d0 to d9 | Log of the last ten faults                            |  |
| dd       | Clears the fault log: press "OK" for 7 s (Fig.31).    |  |

# **TECHNICAL SPECIFICATIONS**

|  |                                     | Dexxo Pro 800 RTS                                       | Dexxo Pro 1000 RTS  |  |
|--|-------------------------------------|---|---|--|
| BASIC TECHNICAL CHARACTERIS              | TICS                                |   |   |  |
| Mains supply                             |                                     | 230 V   | - 50 Hz   |  |
| Max. power consumption Standby-Operation |                                     | 5 W - 600 W (with 5                                     | 00 W remote lighting)   |  |
| Traction force                           | Peak force                          | 800 N   | 1000 N  |  |
|  | Starting force (1)                  | 650 N   | 800 N   |  |
| Use                                      |                                     | 20 cycles max. per day with a standard rail - 50 cyc    | les max, per day with a high performance rail tested                              |  |
| Number of Opening/Closing cycles per day |                                     | for 36,500 cycles with a standard rail and              | 90,000 cycles with a high performance rail  |  |
| Max. speed                               |                                     |   | cm/s  |  |
| Programming interface                    |                                     |   | acter LCD display   |  |
| Operating temperature                    |                                     |   | - indoor dry - IP 20  |  |
| Travel end limits                        |                                     |   | pper at opening   |  |
|  |                                     |   | it position at closing  |  |
| Electrical insulation                    |                                     |   |   |  |
|  |                                     | Class 2: double   |   |  |
| Built in lighting                        |                                     |   | BA15s socket  |  |
| Somfy radio frequency                    |                                     |   | 3.42 MHz  |  |
| Number of channels that can be memorised |                                     | 3   | 12  |  |
| CONNECTIONS                              |                                     | '   |   |  |
| Safety input                             | Туре                                | Dry cor   | tact: NC  |  |
| outory input                             | Compatibility                       |   | I - Sensor strip with dry contact output  |  |
| Pedestrian door safety input             | compatibility                       |   | tact: NC  |  |
| Wired control input                      |                                     |   | tact: NO  |  |
| Remote lighting output                   |                                     | Dry con   |   |  |
| Remote lighting output                   |                                     | 230 V - 500 W   | - class 2   |  |
| Orange light output                      |                                     | 24 V - 15 W with built in flashing control              |   |  |
| 24 V controlled power supply output      |                                     |   | ectric TX/RX cell self-test   |  |
| Safety input test output                 |                                     | Yes: for possible reflex cell or sensor strip self-test |   |  |
| Accessory power supply output            |                                     | 24 V - 50   | 0 mA max  |  |
| Remote aerial input                      |                                     | Yes: RTS aerial com                                     | oatible (Réf. 2400472)  |  |
| Backup battery input                     |                                     | Yes: battery pack compatible (Réf. 9001001)             |   |  |
|  | Autonomy                            | 24 hours: 5 to 10 cvc                                   | es depending on door  |  |
|  | ,                                   |   | ie: 48 hours  |  |
| OPERATION                                |                                     |   |   |  |
| Forced operation mode                    |                                     | By pressing and holding                                 | the motor control button  |  |
| Independent lighting control             |                                     |   | note lighting   |  |
| Lighting time delay (after movement)     |                                     |   | e : 60 s to 600 s   |  |
| Automatic closing mode                   |                                     |   | time delay from 10 to 120 s   |  |
| Orange light pre-warning                 |                                     | Programmable: with or without r                         | prior warning (duration set to 2 s)   |  |
| Safety input operation                   | While closing                       |   | al re-opening - Full reopening  |  |
| ourory input operation                   | Before opening                      |   | fect or motion refused  |  |
|  | (Dangerous Movement Area Accessible | l rogrammazion no on                                    |   |  |
|  | to the Public)                      |   |   |  |
| Built-in obstacle detection              |                                     | Adjustable ser  | sitivity: 4 levels  |  |
| Operation when an obstacle is detected   |                                     |   | e-opening or full reopening   |  |
| Preset partial opening command           |                                     |   | able partial opening position   |  |
| Progressive start up                     |                                     |   | es  |  |
| Opening speed                            |                                     |   | to 18 cm/s: 10 possible values  |  |
| Closing speed                            |                                     |   | to 18 cm/s: 10 possible values  |  |
| Closure approach speed                   |                                     |   | wn, short slowdown zone (30 cm),  |  |
|  |                                     | long slowdow  | n zone (50 cm)  |  |
| Troubleshooting                          |                                     |   | le counter with obstacle detection, number of radio he last ten defects recorded. |  |
|  |                                     |   | חב ומסו ובח עפובטוס ובטטועבע.   |  |

Maximum load for motor to start and drive door for at least 5 cm (according to RAL-GZ definition).

### Dimensions



somfy.com

### Listes des filiales / Somfy weltweit / Lists of subsidiaries Lista oddziałów / Elenco delle filiali / Lijst van filialen

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PATENTS AND DESIGN PATENTS PENDING FOR SOME COUNTRIES (e.g. : US) Somfy SAS, capital 20.000.000 Euros, RCS Annecy 303.970.230 - 05/2013

